



## Optimization of Single Screw Extrusion

**António Gaspar-Cunha**

*Institute of Polymers and Composites,*

*Department of Polymer Engineering, University of Minho*

*Guimarães, Portugal*

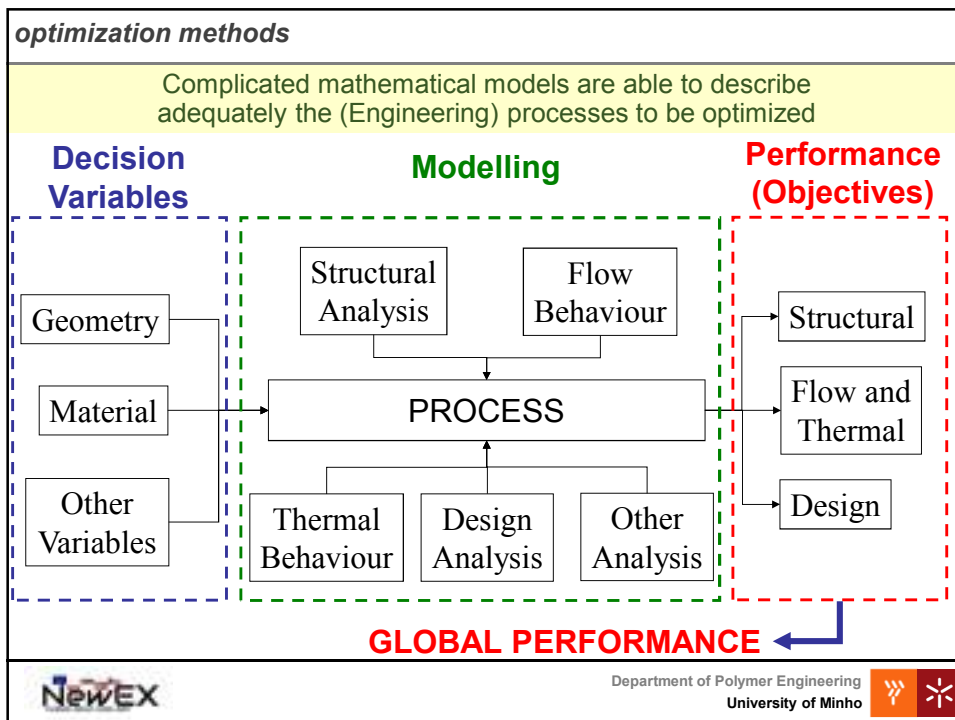
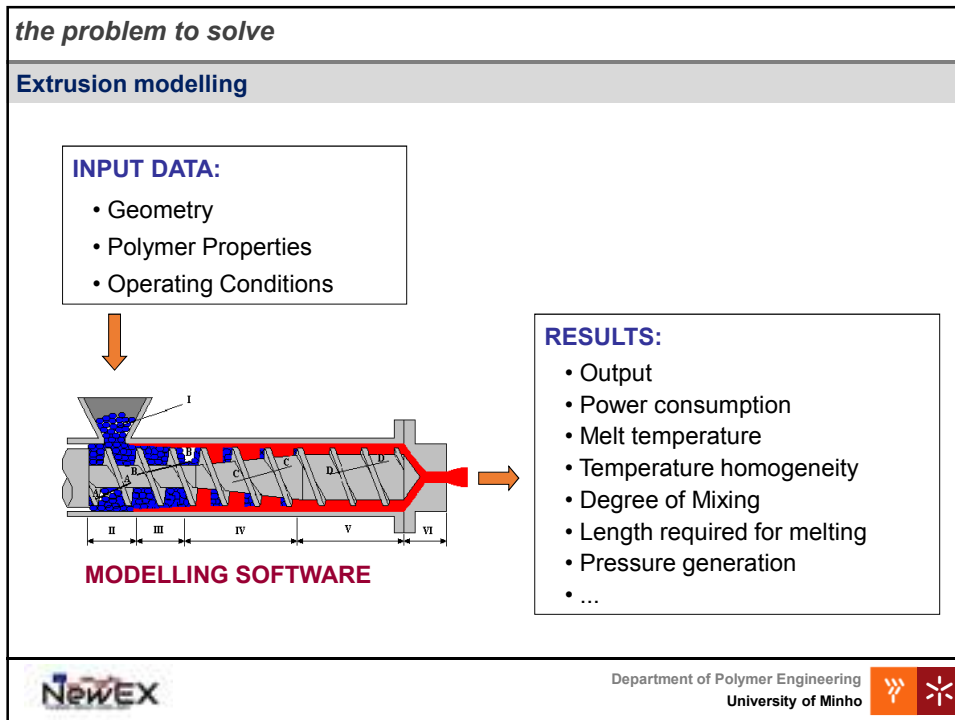
### *contents*

- **The problem to solve**
- **Optimization methods**
- **Evolutionary algorithms**
- **Multi-objective evolutionary algorithms**
- **Results**



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**optimization methods**

*Approaches to optimize the processes (e.g., set the operating conditions, design machines, etc...):*

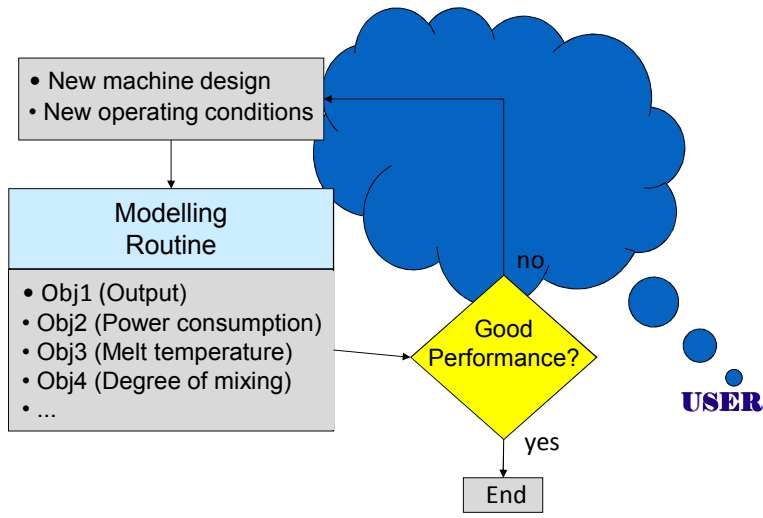
- Use empirical knowledge;
- Use computational tools on a trial and error basis;
- Solve the inverse problem;
- Perform a partial process optimization;
- Develop a global optimization procedure.





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**optimization methods**

**Use computational tools on a trial and error basis**

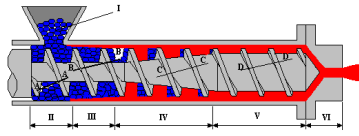




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**optimization methods**

**Solve the inverse problem**



**Direct problem:**

- Geometry
- Material properties
- Operating conditions

**Inverse problem:**

- Material properties
- Output
- Power consumption
- Melt temperature
- Degree of mixing
- ...


Governing equations

→


Governing equations

- Output
- Power consumption
- Melt temperature
- Degree of mixing
- ...

- Geometry
- Operating conditions
- ...

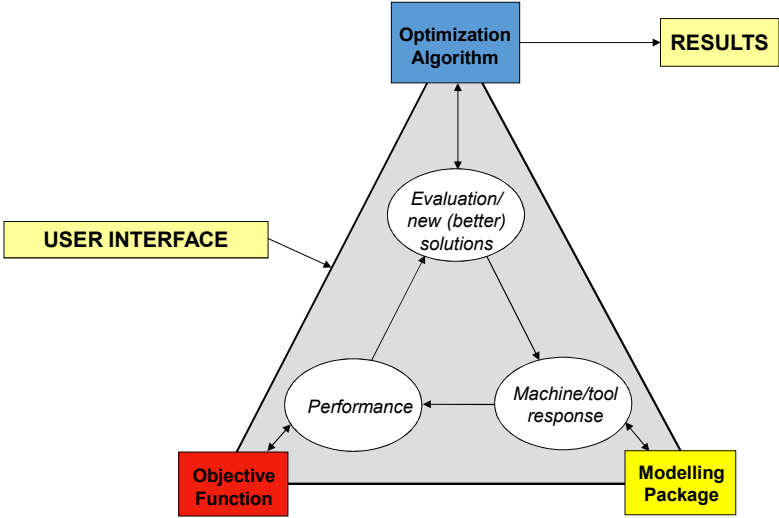



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**optimization methods**

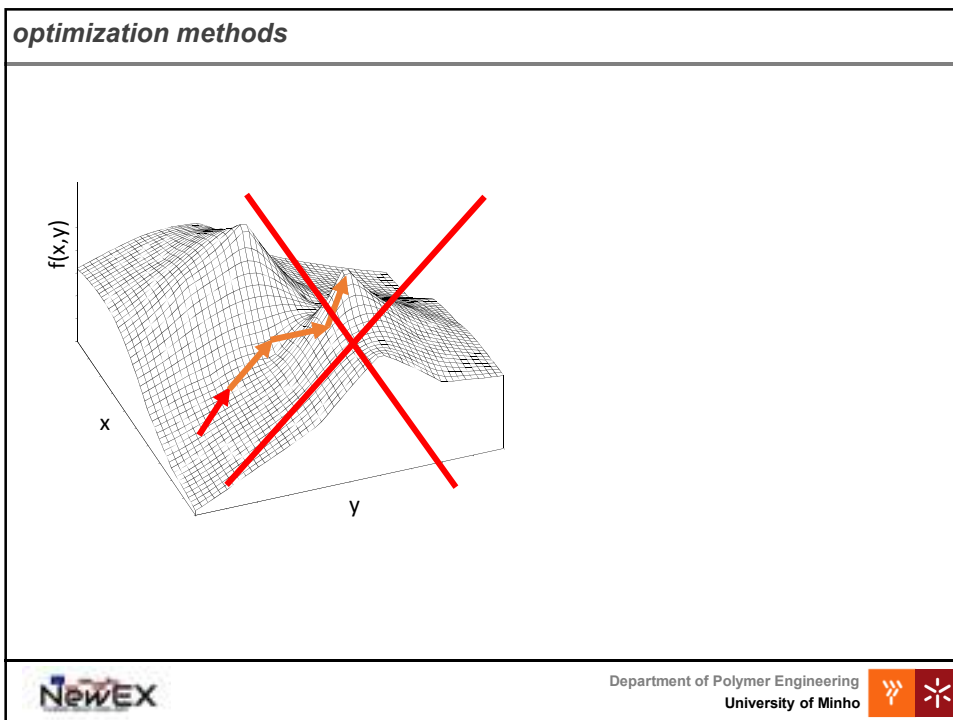
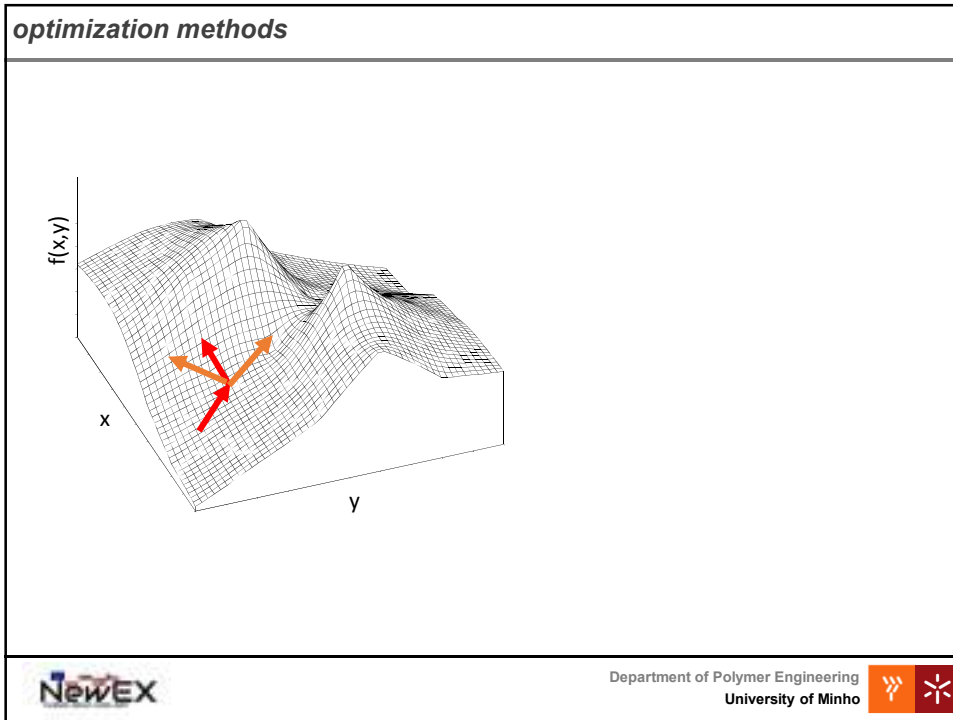
**Develop a global optimization procedure**

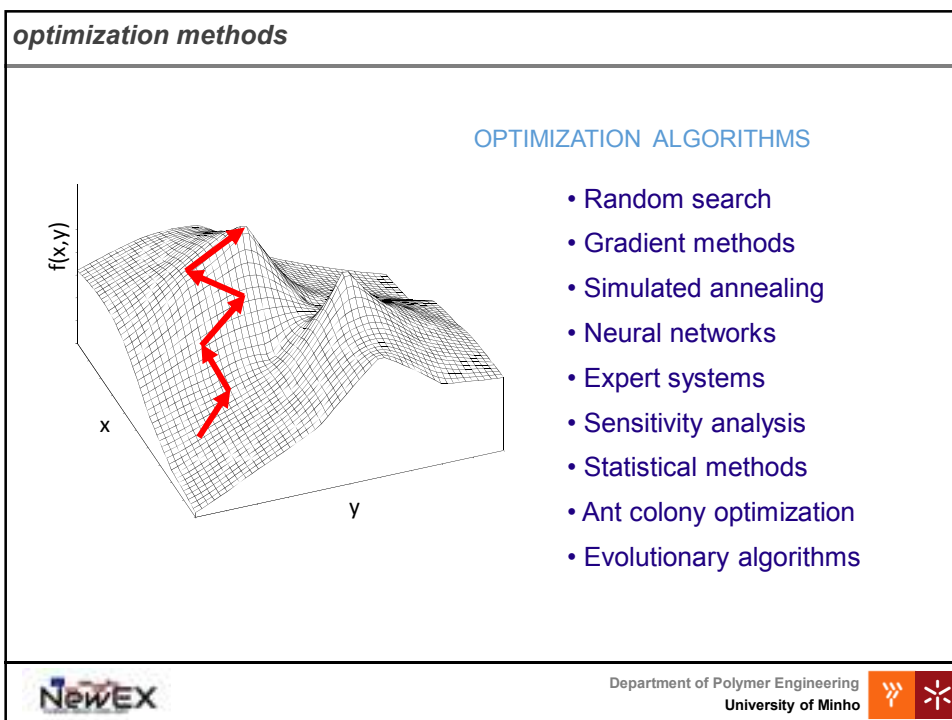
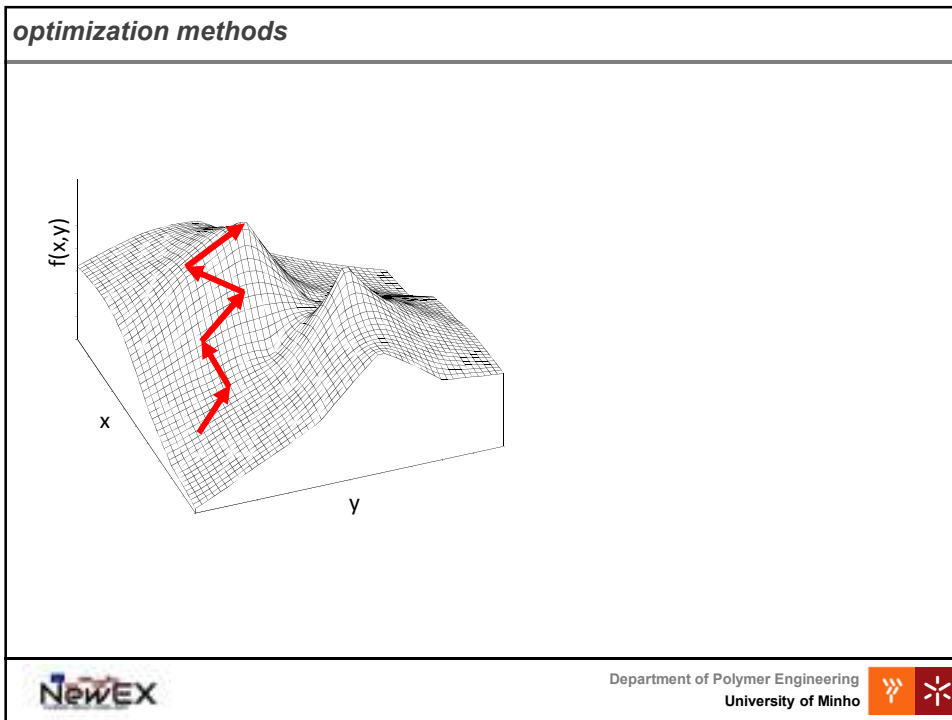




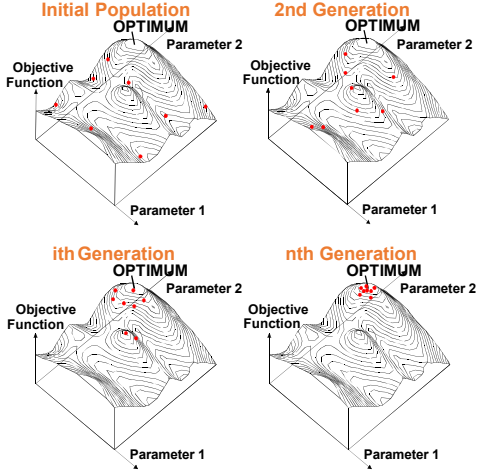
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**evolutionary algorithms**



- Search uses a population of points
- Able to distinguish between local and absolute maxima
- Do not require derivatives nor other knowledge on the process (BLACK BOX)
- Require significant computation resources

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**evolutionary algorithms**

The role of optimisation is to find the best set of parameters that optimise an objective function, particularly by improving the performance in the direction of some optimal point or points:

$$\begin{aligned} &\text{maximise}_{x \in \Omega} && f(x_i) && i = 1, \dots, n \\ &\text{subject to} && g_j(x_i) \geq 0 && j = 1, \dots, J \\ &&& h_k(x_i) = 0 && k = 1, \dots, K \end{aligned}$$



where  $x$  is a vector of  $n$  and  $\Omega \subset \mathfrak{R}^n (\Omega = \{x \in \mathfrak{R}^n : l \leq x \leq u\})$

$f$  is the objective function of the  $n$  parameters  $x_i$ ,  $g_j$  are the  $J$  ( $J \geq 0$ ) inequality constraints, and  $h_k$  are the  $K$  ( $K \geq 0$ ) equality constraints.

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**evolutionary algorithms**



- Evolutionary Algorithms (EAs) are stochastic search and optimisation methods that mimic natural evolution through genetic operators like crossover and mutation.
- They work with a population of points, each one representing a possible solution in the search space.
- Each individual has a value associated to it (fitness or objective function), which is a measure of its performance on the system.
- Individuals with greater performance have a bigger opportunity for reproduction, i.e. to pass their characteristics to future.

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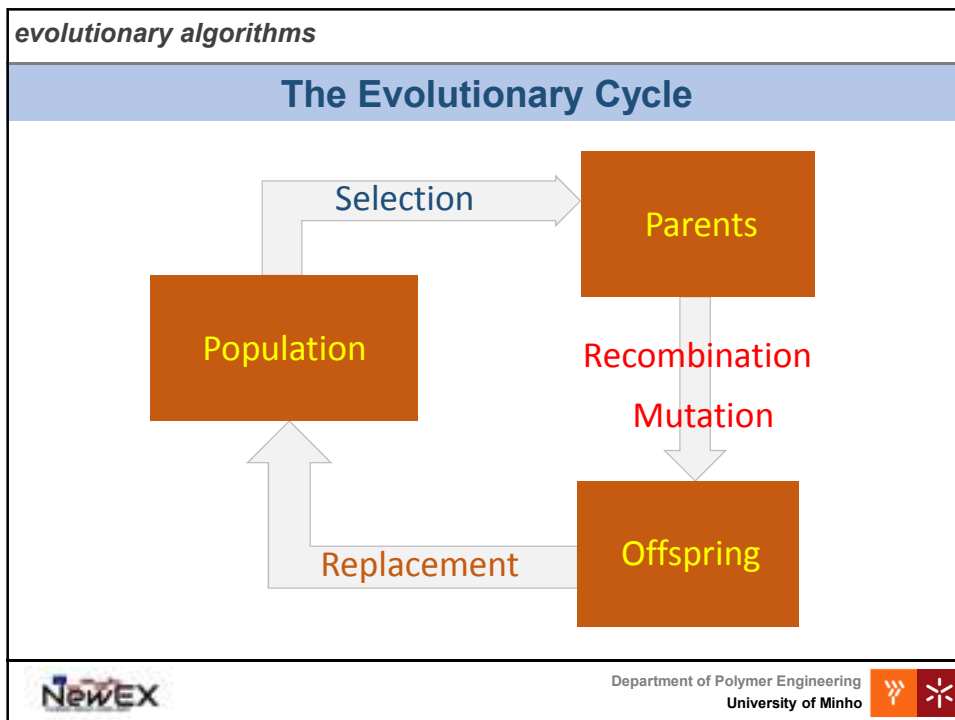
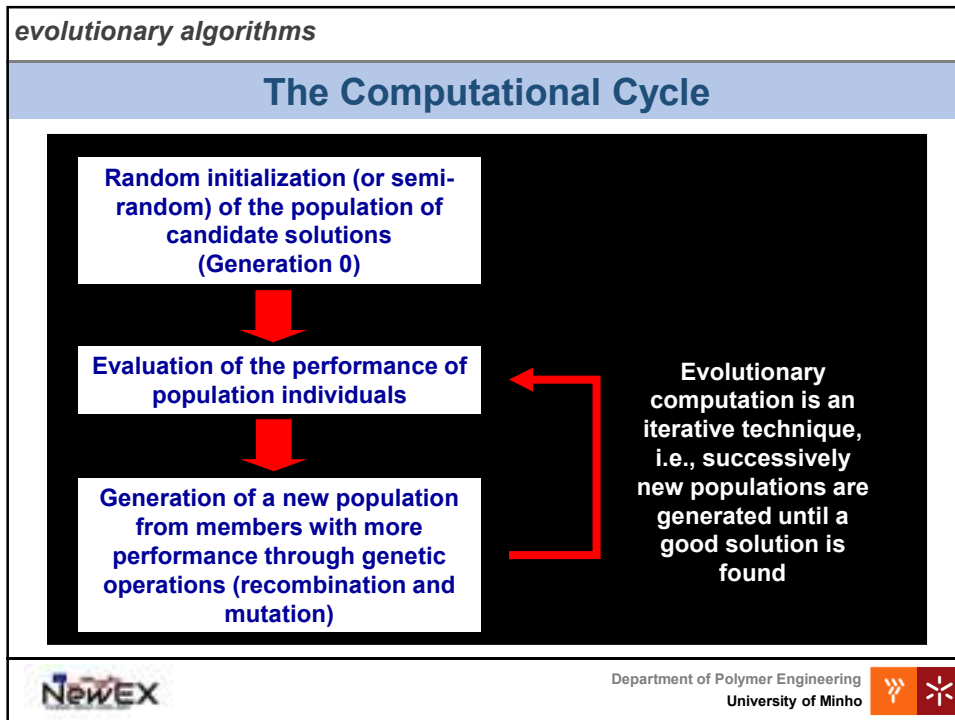
**evolutionary algorithms**

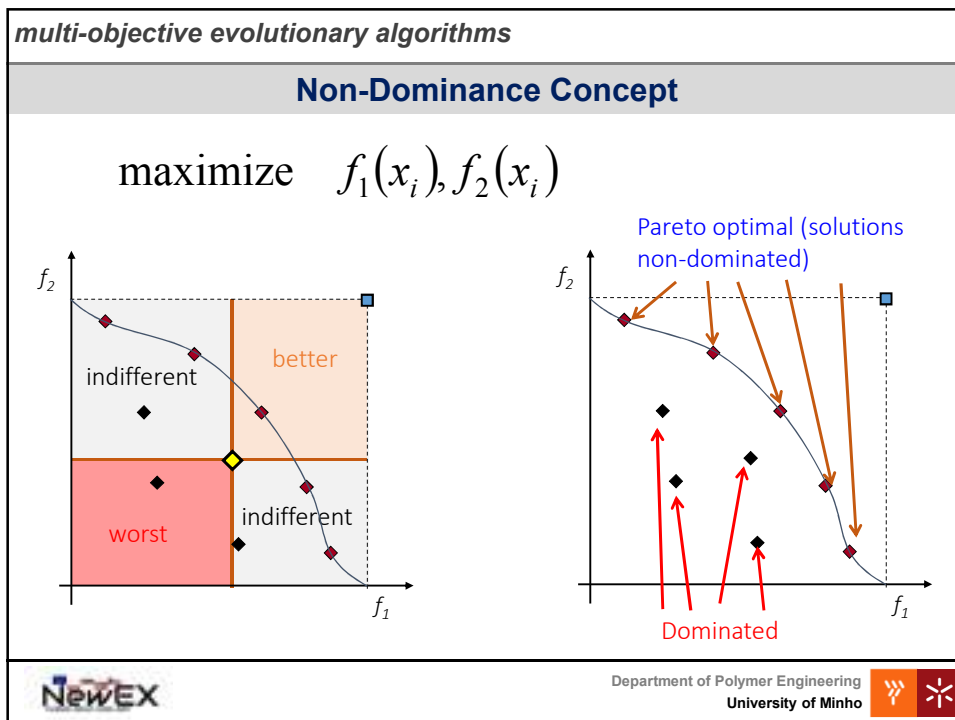
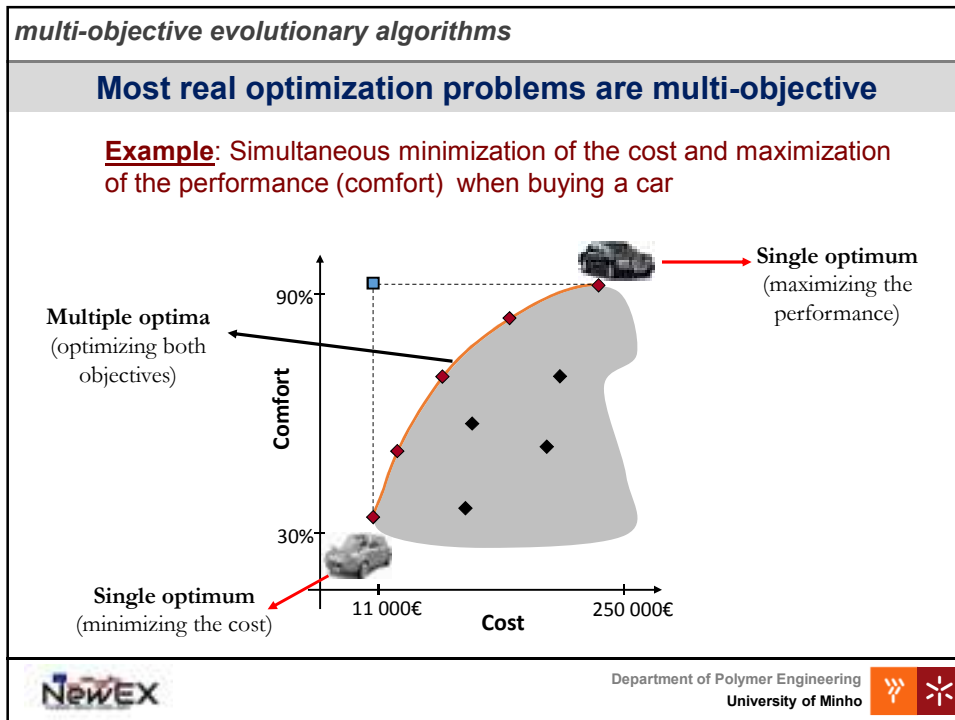
### Evolutionary Computation – THE METAPHOR

Natural Evolution		Evolutionary Computation
Individual		Solution
Performance		Quality
Environment		Problem

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*multi-objective evolutionary algorithms*

### Multi-Objective Optimization Problem

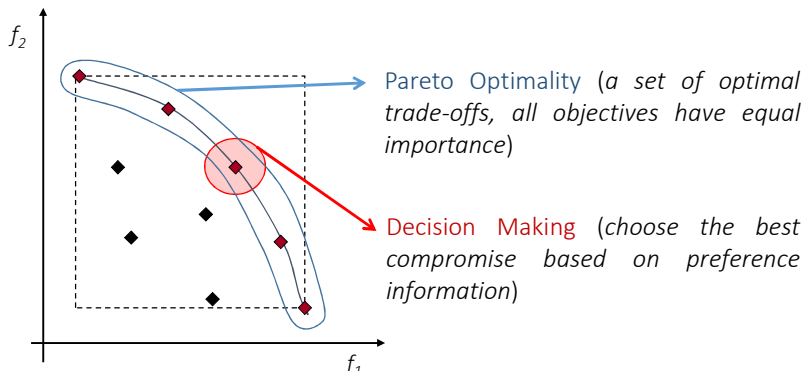
$$\begin{aligned} \min_{x_i} \quad & f_l(x_i) & i = 1, \dots, n & \quad l = 1, \dots, M \\ \text{subject to} \quad & g_j(x_i) = 0 & j = 1, \dots, J \\ & h_k(x_i) \geq 0 & k = 1, \dots, K \end{aligned}$$

where  $f_l$  are the  $M$  objective functions of the  $n$  parameters  $x_i$ , and  $g_j$  and  $h_k$  are the  $J$  equality ( $J \geq 0$ ) and  $K$  inequality ( $K \geq 0$ ) constraints, respectively

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*multi-objective evolutionary algorithms*

### Decision making



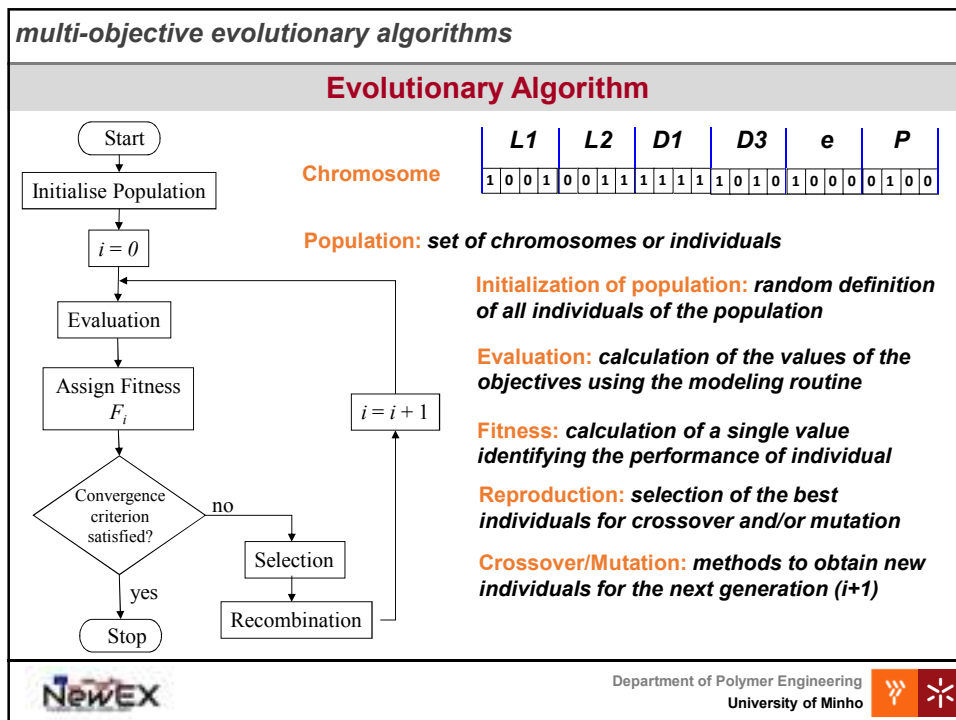
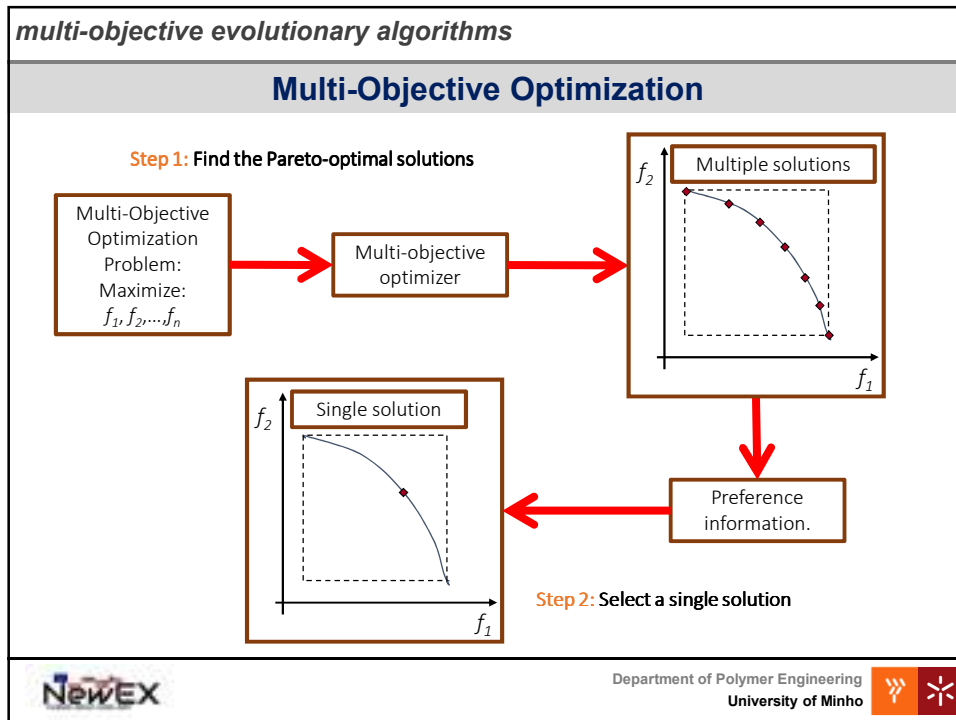
$f_2$

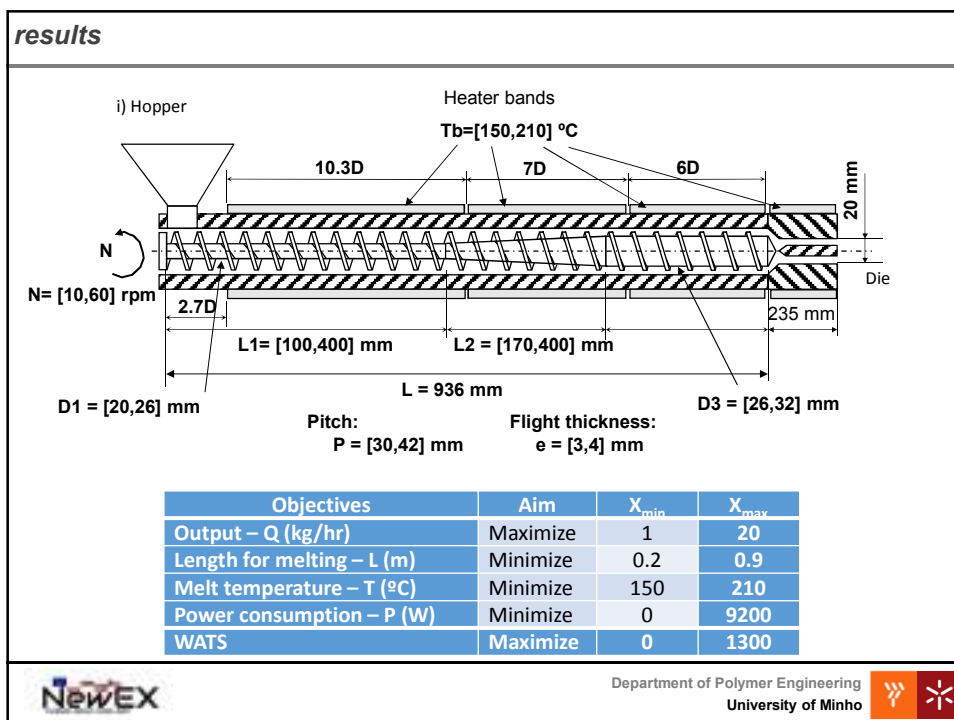
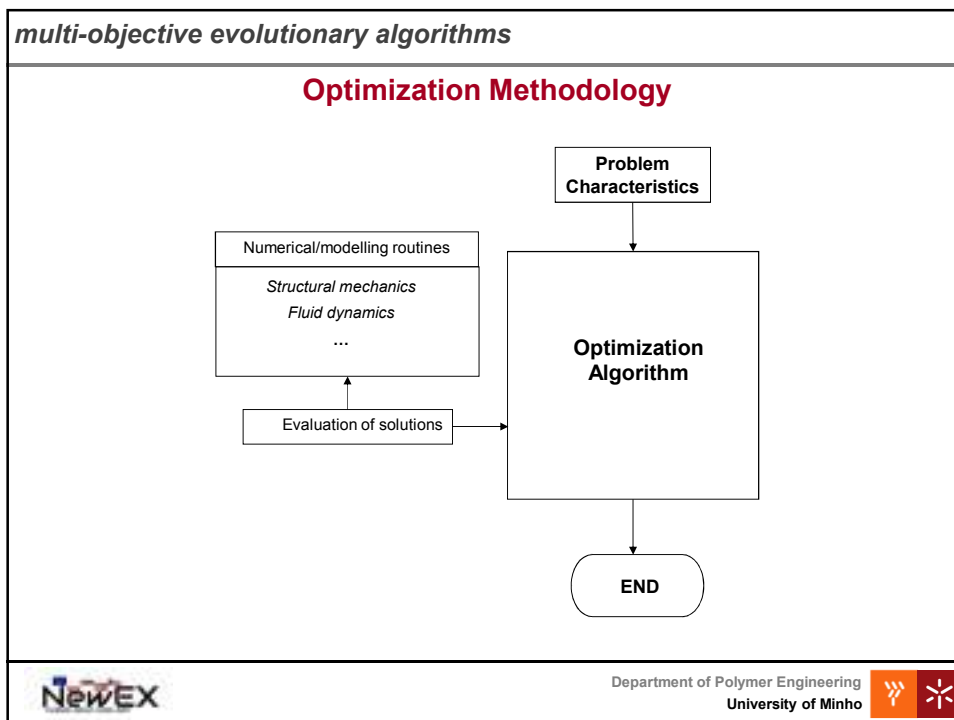
$f_1$

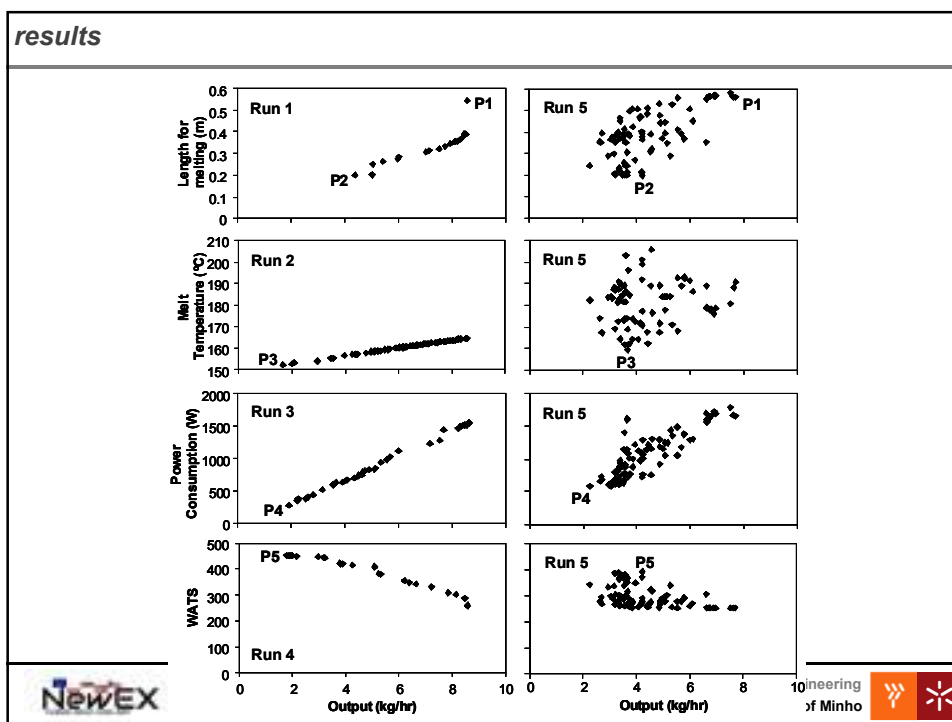
Pareto Optimality (a set of optimal trade-offs, all objectives have equal importance)

Decision Making (choose the best compromise based on preference information)

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**WHAT DO WE NEED FROM PREVIOUS STEPS OF THE PROJECT?**

- Polymer properties
- Operating conditions
- System geometry

**WHAT DO WE NEED FROM PREVIOUS STEPS OF THE PROJECT?****Polymer properties**

- Friction coefficients (very important);
- Solid density =  $f(P,T)$ ;
- Melt density =  $f(P,T) - PVT$ ;
- Thermal conductivity (solid and melt);
- Heat capacity (solid and melt);
- Heat of fusion;
- Melting temperature;
- Viscosity =  $f(T, \text{shear rate})$



# Thanks!

## Debate

